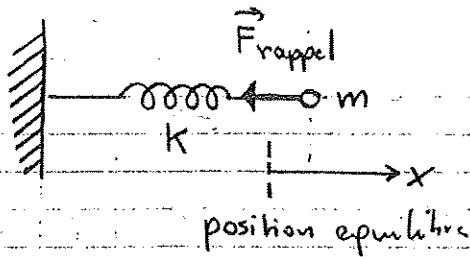


Mouvement périodique d'une masse = oscillateur



$$\sum \vec{F} = m \vec{a}$$

$$\underbrace{\vec{P} + \vec{R}}_{\vec{0}} + \vec{F}_{\text{rappel}} = m \vec{a} \quad \text{sans frottement}$$

$\vec{0} \rightarrow$  Pb en 1 dimension

$$m \vec{a} = \vec{F}_{\text{rappel}} \rightarrow m \frac{d^2 x(t)}{dt^2} \vec{e}_x = -k x \vec{e}_x$$

$$\frac{d^2 x(t)}{dt^2} + \frac{k}{m} x(t) = 0$$

$$\frac{d^2 x(t)}{dt^2} + \omega_0^2 x(t) = 0$$

$$\boxed{\omega_0^2 = \frac{k}{m}}$$

A.N.  $m = 0,1 \text{ kg}$   $k = 10 \text{ kg} \cdot \text{s}^{-2}$   $\omega_0 = \sqrt{\frac{10}{0,1}} = 10 \text{ rad} \cdot \text{s}^{-1}$

éq. caractéristique  $e^{rt} \rightarrow r^2 + \omega_0^2 = 0 \quad r = \pm i \omega_0$

$x(t) = A e^{i \omega_0 t} + B e^{-i \omega_0 t}$  combinaison linéaire

conditions initiales.  $x(t=0) = x_0 \quad \frac{dx}{dt}(t=0) = 0$

$$x(t=0) = A + B = x_0$$

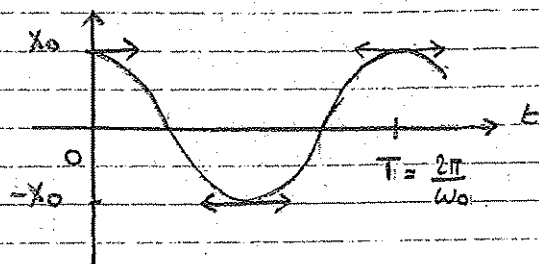
$$\frac{dx}{dt}(t) = i \omega_0 (A e^{i \omega_0 t} - B e^{-i \omega_0 t}) \quad \frac{dx}{dt}(t=0) = i \omega_0 (A - B) = 0 \rightarrow A = B = \frac{x_0}{2}$$

$$\text{solution } x(t) = \frac{x_0}{2} (e^{i \omega_0 t} - e^{-i \omega_0 t}) = x_0 \cos \omega_0 t$$

on peut montrer qu'on obtient le même résultat avec  $x_1(t)$ ,  $x_2(t)$  et  $x_3(t)$

$x_1(t) \rightarrow A_1 = x_0, B_1 = 0 \quad x_2(t) \rightarrow A_2 = x_0, \phi_2 = 0$

$x_3(t) \rightarrow A_3 = x_0, \phi_3 = \frac{\pi}{2}$



$$\boxed{T = \frac{2\pi}{\omega_0}}$$